

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	45600	(detect\$4 or scan\$4 or captur\$4 or read\$4 or sensor\$3)same(container\$4 or bottl\$4 or packag\$4)same(mov\$6 or tranv\$6 or transfer\$4)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:52
L2	14709	1 same(ly\$4 or sid\$3 or rest\$4 or fall\$4 or collaps4 or drop\$4 or down\$4)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:53
L3	5327	2 same(return\$4 or reject\$3 or remov\$4 or reinsert\$3 or push\$3 or redirect\$4)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:56
L4	1815	3 same(bottom\$2 or mouth\$3 or top\$2)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:56
L5	2070	3 same(bottom\$2 or mouth\$3 or top\$2 or inlet\$3 or outlet\$4)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:57
L6	23	5 same(video\$2)	US-PGPUB; USPAT	OR	ON	2006/05/24 13:09
L7	177	5 same(empty\$3)	US-PGPUB; USPAT	OR	ON	2006/05/24 11:36
L8	469	5 same(empty\$3 or hollow\$2 or vac\$6)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:57
L9	62	8 same(user\$2 or person\$3 or viewer\$4 or operator\$3 or human\$3)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:58
L10	29781	(detect\$4 or scan\$4 or captur\$4 or read\$4 or sensor\$3)same(container\$4 or bottl\$4)same(mov\$6 or tranv\$6 or transfer\$4)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:52
L11	29783	(detect\$4 or scan\$4 or captur\$4 or read\$4 or sensor\$3)same(container\$4 or bottl\$4)same(mov\$6 or tranf\$6 or transfer\$4)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:52
L12	30475	(detect\$4 or scan\$4 or captur\$4 or read\$4 or sensor\$3)same(container\$4 or bottl\$4)same(mov\$6 or trans\$6 or transfer\$4)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:52
L13	10410	12 same(ly\$4 or sid\$3 or rest\$4 or fall\$4 or collaps4 or drop\$4 or down\$4)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:53
L14	3955	13 same(return\$4 or reject\$3 or remov\$4 or reinsert\$3 or push\$3 or redirect\$4)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:56

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L15	1377	14 same(bottom\$2 or mouth\$3 or top\$2)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:56
L16	1377	15 same(bottom\$2 or mouth\$3 or top\$2 or inlet\$3 or outlet\$4)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:57
L17	281	16 same(empty\$3 or hollow\$2 or vac\$6)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:57
L18	43	17 same(user\$2 or person\$3 or viewer\$4 or operator\$3 or human\$3)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:58
L19	1	"5603363".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:07
L20	1	"5299715".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:08
L21	1	"4886190".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:08
L22	1	"4850387".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:08
L23	1	"5794519".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:08
L24	1	"5773067".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:08
L25	1	"5603254".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:09
L26	1	"5501525".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:09
L27	1	"5692029".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:14
L28	1	"5675516".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:14
L29	1	"5675516".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:14
L30	1	"5443164".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:15
L31	1	"5443164".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:15
L32	1	"5150307".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:15
L33	1	"5150307".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:15
L34	1	"5007096".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:16


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Key: IEEE JNL = IEEE Journal or Magazine, IEE JNL = IEE Journal or Magazine, IEEE CNF = IEEE Conference, IEE CNF = IEE Conference, IEEE STD = IEEE Standard

1. **Pose detection of moving vehicle using rotating LSB (laser slit beam)**
Sun Ho Kim; Kun Kook Park; Kyoung Taik Park; Jung Hwan Ahn;
Industrial Electronics, 2001. Proceedings. ISIE 2001. IEEE International Symposium on
Volume 1, 12-16 June 2001 Page(s):83 - 88 vol.1
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2. **Remote bar-code localisation using mathematical morphology**
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Volume 2, 13-15 July 1999 Page(s):642 - 646 vol.2
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3. **Measurement of 3D spreader position for automatic landing system**
Jung Jae Lee; Gi Gun Nam; Bong Ki Lee; Jang Myung Lee;
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4. **Manipulation support system for large serving robots**
Hildebrandt, A.; Sawodny, O.;
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5. **LOCO GPSI: Preserve the GPS advantage for defense and security**
Simonsen, K.; Suycott, M.; Crumplar, R.; Wohlfel, J.;
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6. **Signal processing applied to the dolphin-based sonar system**
Houser, D.; Martin, S.; Phillips, M.; Bauer, E.; Herrin, T.; Moore, P.;
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7. **Parallel Lanczos bidiagonalization for total least squares filter in robot navigation**
Yang, L.T.;
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8. **CCD camera calibration for underwater laser scanning system**
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9. **Fast centroid estimation algorithm for high-rate detectors based on a two-point Gaussian fit**
Pietraski, P.J.; Zojceski, Z.;
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10. **Acoustical/optical technology integration with a manned submersible and a ROV for the investigation of a radioactive materials disposal site and a sewage diffuser outfall**
Lindsay, J.A.; Coles, B.; Babb, I.; Tomey, D.; Liebman, M.; Nevis, A.; Taylor, J.S., Jr.; Askew, T., Jr.; Bell, W.J.; Kez K.; Louft, H.; Fredette, T.; Regan, R.;
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11. **The design of a radar-based navigation system for large outdoor vehicles**
Durrant-Whyte, H.; Bell, E.; Avery, P.;
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12. **Environmental characterization with magnetics and STOLS**
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13. **MDR for law enforcement [motion detector radar]**
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14. **Iterative reconstruction and statistical optimization for the nondestructive assay of distributed gamma sou**
in a large nuclear waste container
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16. **Exploring data rate limitations of channel front-ends for rigid disk drives**
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- 18. Model gantry crane with dynamic feedback swing control**
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- 19. A Scalable Multi-Replication Framework for Data Grid**
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- 20. A Modular Approach to Real-Time Cork Classification Using Image Processing**
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- 22. Utilizing higher order statistics of packet interarrival times for bottleneck detection**
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- 23. View-dependent rendering of multiresolution texture-atlases**
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- 24. Fine water mist fire protection system**
McBride, W.E.;
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- 25. 3D Measurements in Cargo Inspection with a Gamma-Ray Linear Pushbroom Stereo System**
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